

Useful Formulas for Communication Systems

Revision 1.0.3

Author: Jan Molina

Text: *Modern Digital and Analog Communication Systems, 4th Ed. (B.P. Lathi, Zhi Ding)*

Chapter 2

Signal energy

$$E_g = \int_{-\infty}^{\infty} |g(t)|^2 dt$$

Signal power

$$P_g = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |g(t)|^2 dt$$

Signal decomposition

$$e(t) = g(t) - cx(t)$$

$$c = \frac{\int_{t_1}^{t_2} g(t)x(t)dt}{\int_{t_1}^{t_2} x^2(t)dt} = \frac{1}{E_x} \int_{t_1}^{t_2} g(t)x(t)dt$$

$$g(t) \approx c \cdot x(t)$$

Signal correlation

$$\rho = \frac{1}{\sqrt{E_g E_x}} \int_{-\infty}^{\infty} g(t)x(t)dt$$

Signal correlation (General/Complex)

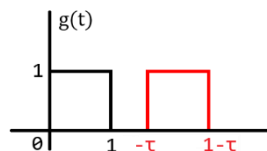
$$\rho = \frac{1}{\sqrt{E_g E_x}} \int_{-\infty}^{\infty} g(t)x^*(t)dt$$

Cross correlation

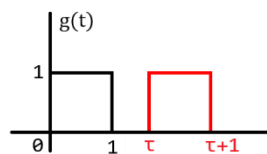
$$\psi_{zg}(\tau) = \int_{-\infty}^{\infty} z(t)g^*(t - \tau)dt = \int_{-\infty}^{\infty} z(t + \tau)g^*(t)dt$$

Auto correlation

$$\psi_g(\tau) = \int_{-\infty}^{\infty} g(t)g(t + \tau)dt$$



$$\psi_g(\tau) = \int_{-\infty}^{\infty} g(t)g(t - \tau)dt$$



Chapter 3 (1/2)

Parseval's Theorem

The energy E_g of a signal $g(t)$ can be obtained from the time domain *OR* the frequency domain.

$$E_g = \int_{-\infty}^{\infty} |G(f)|^2 df$$

ESD (Energy Spectral density)

$$\Psi_g(f) = |G(f)|^2$$

$$E_g = \int_{-\infty}^{\infty} \Psi_g(f) df$$

$$\psi_g(\tau) \leftrightarrow \Psi_g(f)$$

PSD Power spectral density

$$S_g(f) = \lim_{T \rightarrow \infty} \frac{|G_T(f)|^2}{T} = \lim_{T \rightarrow \infty} \frac{\Psi_{gT}(f)}{T}$$

$$P_g = \int_{-\infty}^{\infty} S_g(f) df = 2 \int_0^{\infty} S_g(f) df$$

Time autocorrelation $R(\tau)$

$$R_g(\tau) = \lim_{T \rightarrow \infty} \int_{-T/2}^{T/2} g(t)g(t - \tau) dt = \lim_{T \rightarrow \infty} \frac{\psi_{gT}(\tau)}{T}$$

$$R_g(\tau) = R_g(-\tau)$$

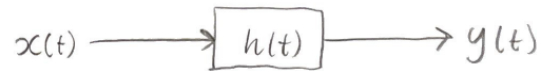
$$R_g(\tau) \leftrightarrow S_g(f)$$

Power is the "mean square" value

$$P_g = \overline{g^2(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} g^2(t) dt = \lim_{T \rightarrow \infty} \frac{E_{gT}}{T}$$

Chapter 3 (2/2)

Input and output PSD and ESD



$$Y(f) = H(f) \cdot X(f)$$

$$|Y(f)|^2 = |H(f)|^2 |X(f)|^2$$

Output ESD

$$\Psi_y(f) = |H(f)|^2 \cdot \Psi_x(f)$$

Output PSD

$$S_y(f) = |H(f)|^2 \cdot S_x(f)$$

$$P_y = \int_{-\infty}^{\infty} S_y(f) df = 2 \int_0^{\infty} S_y(f) df$$

PSD of modulated signals

For a power signal $g(t)$ modulated by a cosine wave with frequency f_0 where $f_0 \geq B$, that is

$$\phi(t) = g(t) \cos(2\pi f_0 t),$$

the PSD and power are

$$S_\phi(f) = \frac{1}{4} [S_g(f + f_0) + S_g(f - f_0)]$$

$$P_\phi = \frac{1}{2} P_g$$

Pre-computed PSDs

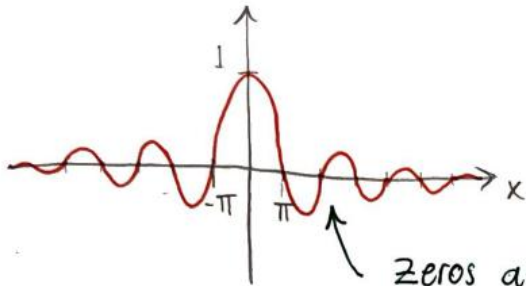
$$g(t) = C \cdot \cos(2\pi f_0 t + \theta_0)$$

$$R_g(\tau) = \frac{C^2}{2} \cos(2\pi f_0 \tau)$$

$$S_g(f) = \frac{C^2}{4} [\delta(f - f_0) + \delta(f + f_0)]$$

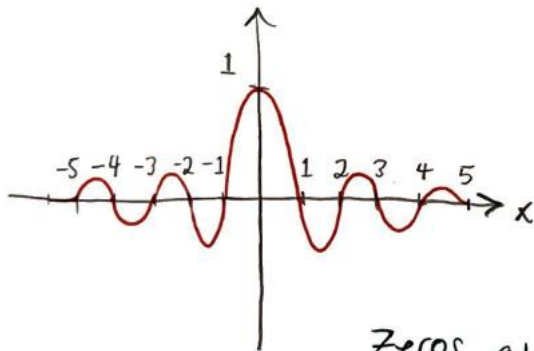
Useful functions – Sinc

Regular sinc



$$\text{sinc}(x) = \frac{\sin(x)}{x}$$

Normalized sinc



$$\text{sinc}_{\pi}(x) = \frac{\sin(\pi x)}{\pi x}$$

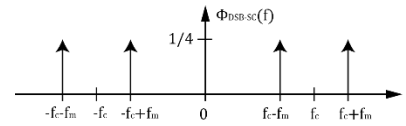
Zeros at $n = \pm 1, \pm 2, \pm 3, \dots$

Chapter 4

DSB-SC modulated signal

$$\Phi_{\text{DSB-SC}}(t) = m(t) \cos(2\pi f_c t)$$

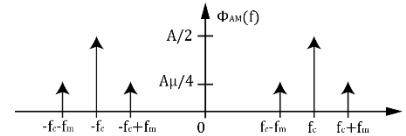
$$\Phi_{\text{DSB-SC}}(f) = \frac{1}{2} [M(f + f_c) + M(f - f_c)]$$



AM modulated signal

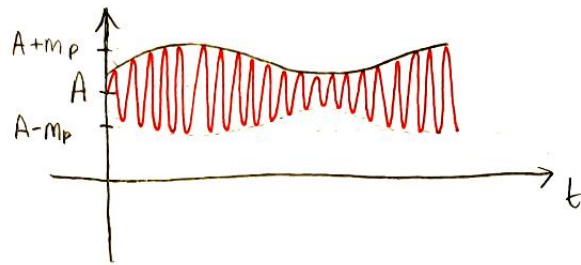
$$\Phi_{\text{AM}}(t) = [A + m(t)] \cos(2\pi f_c t)$$

$$\Phi_{\text{AM}}(f) = \frac{1}{2} [M(f + f_c) + M(f - f_c)] + \frac{A}{2} [\delta(f + f_c) + \delta(f - f_c)]$$



Modulation index (AM)

$$\mu = \frac{m_p}{A}$$



Carrier and Sideband power

$$P_c = \frac{A^2}{2}$$

$$P_s = \frac{1}{2} \overline{m^2(t)} = \frac{1}{2} \cdot \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} m^2(t) dt$$

$$P_{\text{total}} = P_c + P_s$$

Power efficiency

$$\eta = \frac{\text{useful power}}{\text{total power}} = \frac{P_s}{P_c + P_s}$$

Time domain representation of SSB signals

$$\phi_{\text{USB}}(t) = m(t) \cos(\omega_c t) - m_h(t) \sin(\omega_c t)$$

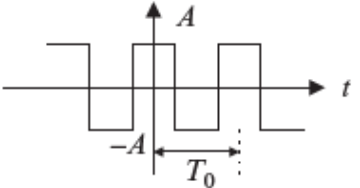
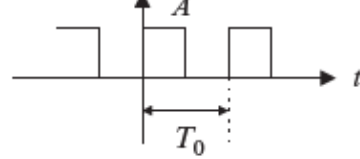
$$\phi_{\text{LSB}}(t) = m(t) \cos(\omega_c t) + m_h(t) \sin(\omega_c t)$$

$$\phi_{\text{SSB}}(t) = m(t) \cos(\omega_c t) \mp m_n(t) \sin(\omega_c t)$$

Demodulation

$$\phi_{\text{SSB}}(t) \cdot 2 \cos(\omega_c t) = m(t) + [m(t) \cos(2\omega_c t) \mp m_h(t) \sin(2\omega_c t)]$$

Fourier Series expansions

<p>Square wave</p> $x(t) = \frac{4A}{\pi} \left(\cos(\omega_0 t) - \frac{1}{3} \cos(3\omega_0 t) + \frac{1}{5} \cos(5\omega_0 t) - \frac{1}{7} \cos(7\omega_0 t) + \dots \right)$	 <p>The graph shows a square wave on a coordinate system with time t on the horizontal axis and amplitude on the vertical axis. The wave oscillates between a maximum value of A and a minimum value of -A. The period of the wave is labeled as T_0. The wave is centered around the t-axis.</p>
<p>Positive square wave</p> $x(t) = \frac{A}{2} + \frac{2A}{\pi} \left(\sin \omega_0 t + \frac{1}{3} \sin 3\omega_0 t + \frac{1}{5} \sin 5\omega_0 t + \frac{1}{7} \sin 7\omega_0 t + \dots \right)$	 <p>The graph shows a positive square wave on a coordinate system with time t on the horizontal axis and amplitude on the vertical axis. The wave is always non-negative, oscillating between a maximum value of A and a minimum value of 0. The period of the wave is labeled as T_0.</p>

Chapter 5 (1/2)

General Form of an Angle-modulated signal

$$\phi_{EM}(t) = A \cos[\theta(t)]$$

Key Attributes

A = amplitude of the angle-modulated signal

ω_c = carrier frequency ($f_c = \frac{\omega_c}{2\pi}$)

$\theta(t)$ = time-varying angle

B = bandwidth of modulating signal m(t)

m_p = amplitude or "peak value" of m(t)

B_{EM} = bandwidth of the angle-modulated signal

k_p = phase sensitivity

k_f = frequency sensitivity

$\Delta\omega$ = frequency deviation ($\Delta f = \frac{\Delta\omega}{2\pi}$)

$\Delta\phi$ = phase deviation

Other attributes

$\omega_i(t) = \frac{d}{dt} \theta(t)$ Instantaneous frequency ($f_i = \frac{\omega_i}{2\pi}$)

$P_{avg} = \frac{A^2}{2}$ Power of an angle-modulated signal

FM-modulated signal

$$\phi_{FM}(t) = A \cos \left[2\pi f_c t + k_f \int_{-\infty}^t m(\alpha) d\alpha \right]$$

$$f_i(t) = f_c + \frac{k_f}{2\pi} m(t)$$

$$B_{FM} = 2(\Delta f + B)$$

$$\Delta f = k_f \frac{m_p}{2\pi}$$

PM-modulated signal

$$\phi_{PM}(t) = A \cos[2\pi f_c t + k_p m(t)]$$

$$f_i(t) = f_c + \frac{k_p}{2\pi} \dot{m}(t)$$

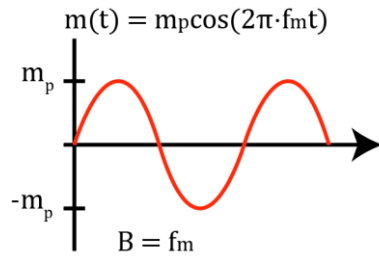
$$B_{PM} = 2(\Delta f + B)$$

$$\Delta f = k_p \frac{[m(t)_{max} - m(t)_{min}]}{2 \cdot 2\pi}$$

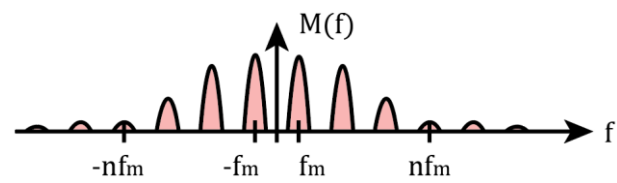
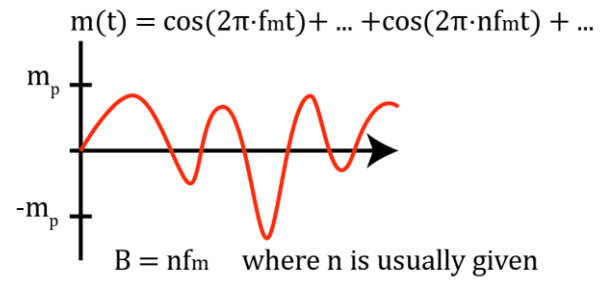
Chapter 5 (2/2)

Bandwidth of $m(t)$ signal

Case 1: Sinusoid



Case 2: Generic analog signal



Chapter 6

Nyquist Rate and Interval

$$R_N = 2B$$

$$T_N = \frac{1}{R} = \frac{1}{2B}$$